

# ECS455: Chapter 5 OFDM

5.3 Implementation: DFT and FFT



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#### **Discrete Fourier Transform (DFT)**

Transmitter produces

$$s(t) = \frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} S_k \exp\left(j\frac{2\pi k}{T_s}t\right), \quad 0 \le t < T_s$$

Sample the signal in time domain every  $T_s/N$  gives sometime rate

$$s(t) \int s[n] = s\left(n\frac{T_s}{N}\right) = \frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} S_k \exp\left(j\frac{2\pi k}{T_s'}n\frac{T_s}{N}\right) = \frac{1}{T_s'} = \frac{1}{T_s'}$$

$$s(t) \int t = \sum_{k=0}^{N-1} S_k \exp\left(j\frac{2\pi kn}{N}\right) = \sqrt{N} \operatorname{IDFT}\left\{S\right\}\left[n\right]$$
where  $\operatorname{IDFT}\left\{S\right\}\left[n\right] = \frac{1}{N} \sum_{k=0}^{N-1} S_k \exp\left(j\frac{2\pi kn}{N}\right)$ 

$$s=\left(S_0 - S_1 - \cdots + S_{N-1}\right)^T$$

We can implement OFDM in the discrete domain!

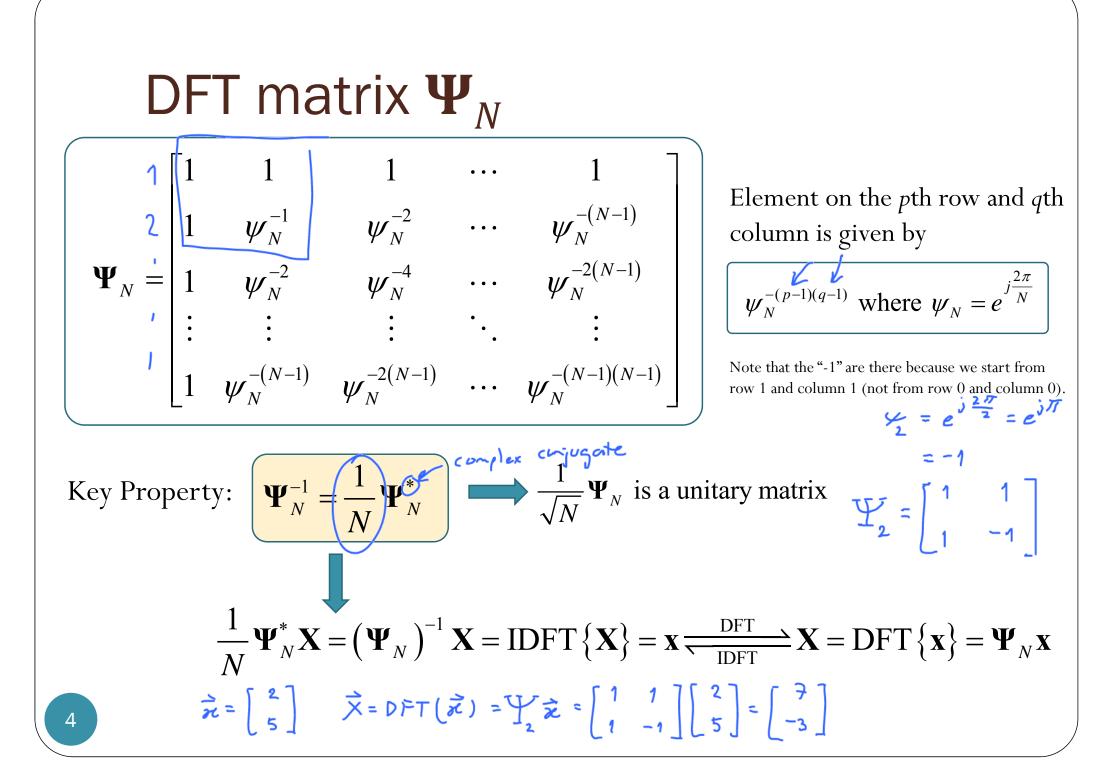
## **Discrete Fourier Transform (DFT)**

Here, we work with *N*-point signals (finite-length sequence (vector) of length *N*) in both time and frequency domain.

$$\mathbf{x} = \begin{pmatrix} x[0] \\ x[1] \\ \vdots \\ x[N-1] \end{pmatrix} \longrightarrow \boxed{\text{DFT}} \longrightarrow \mathbf{X} = \begin{pmatrix} X[0] \\ X[1] \\ \vdots \\ X[N-1] \end{pmatrix}$$
$$\mathbf{X} = \text{DFT} \{\mathbf{x}\} = \Psi_N \mathbf{x}$$

To simplify the notation, we define the **DFT matrix**  $\Psi_N$ .

$$(\boldsymbol{\Psi}_N)^{-1} \mathbf{X} = \text{IDFT} \{\mathbf{X}\} = \mathbf{X} \xrightarrow{\text{DFT}} \mathbf{X} = \text{DFT} \{\mathbf{x}\} = \boldsymbol{\Psi}_N \mathbf{X}$$



$$IDPT(\vec{x}) = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 7 \\ -3 \end{bmatrix} = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$$
  
Discrete Fourier Transform (DFT)

Matrix form:

$$\frac{1}{N}\boldsymbol{\Psi}_{N}^{*}\mathbf{X} = \text{IDFT}\left\{\mathbf{X}\right\} = \mathbf{X} \underbrace{\xrightarrow{\text{DFT}}}_{\text{IDFT}} \mathbf{X} = \text{DFT}\left\{\mathbf{x}\right\} = \boldsymbol{\Psi}_{N}\mathbf{x}$$

Pointwise form:

$$\frac{1}{N}\sum_{k=0}^{N-1} X[k]\psi_N^{nk} = x[n] \xrightarrow{\text{DFT}} X[k] = \sum_{0 \le n < N}^{N-1} x[n]\psi_N^{-nk}$$

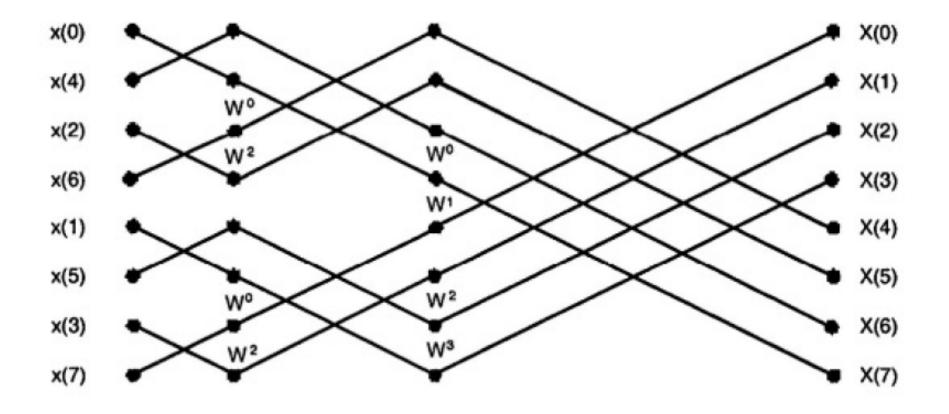
or, equivalently,

$$\frac{1}{N}\sum_{n=0}^{N-1} X[k]e^{jnk\frac{2\pi}{N}} = x[n] \xrightarrow{\text{DFT}} X[k] = \sum_{0 \le n < N}^{N-1} x[n]e^{-jnk\frac{2\pi}{N}}$$

Comparison with Fourier transform

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{j2\pi ft} df \xrightarrow{\mathcal{F}}_{\mathcal{F}^{-1}} x(f) = \int_{-\infty}^{\infty} X(t) e^{-j2\pi ft} dt$$

### Efficient Implementation: (I)FFT



<sup>[</sup>Bahai, 2002, Fig. 2.9]

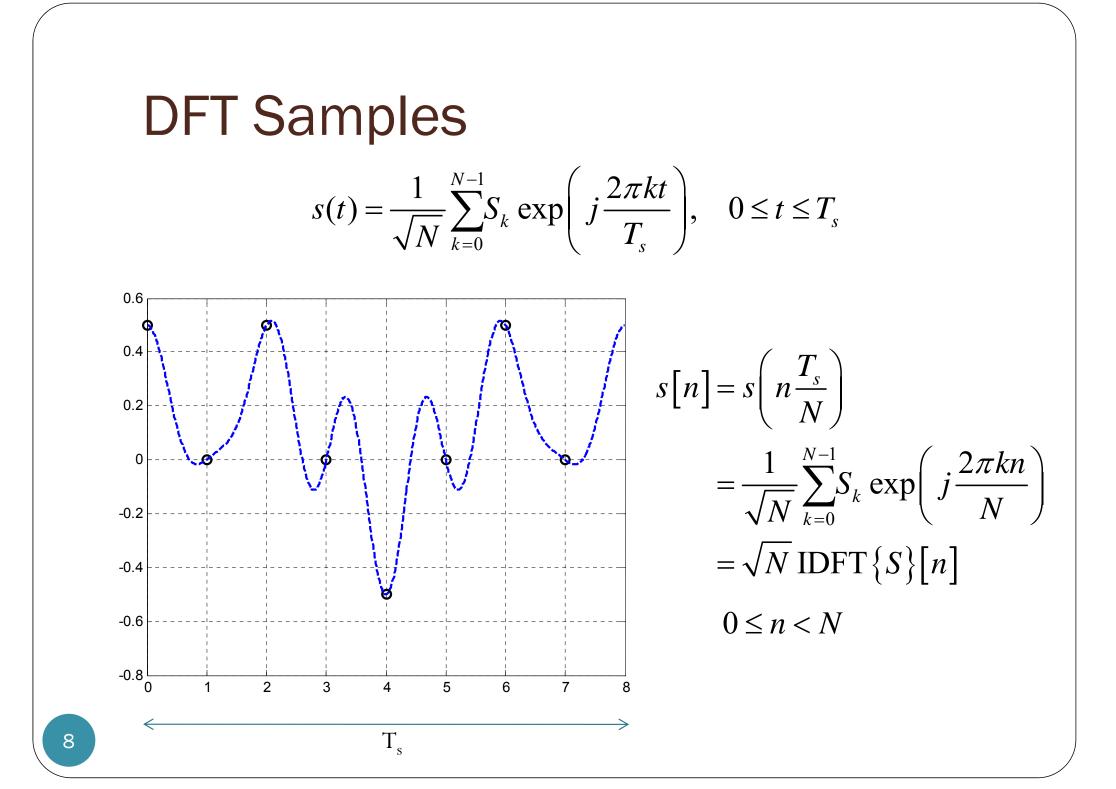
An *N*-point FFT requires only on the order of  $N\log N$  multiplications, rather than  $N^2$  as in a straightforward computation.

## FFT

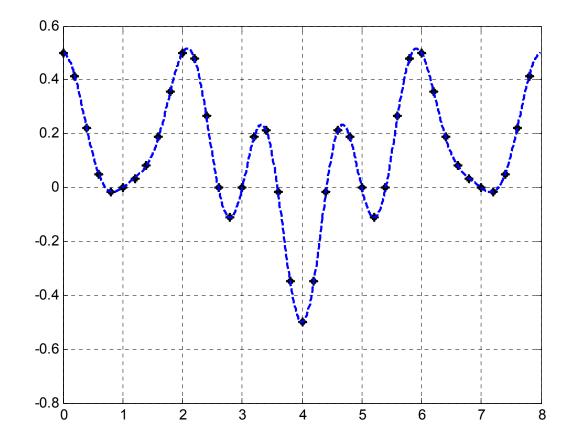
- The history of the FFT is complicated.
- As with many discoveries and inventions, it arrived before the (computer) world was ready for it.
- Usually done with *N* a power of two.
  - Very efficient in terms of computing time
  - Ideally suited to the binary arithmetic of digital computers.
  - Ex: From the implementation point of view it is better to have, for example, a FFT size of 1024 even if only 600 outputs are used than try to have another length for FFT between 600 and 1024.



References: E. Oran Brigham, *The Fast Fourier Transform*, Prentice-Hall, 1974.

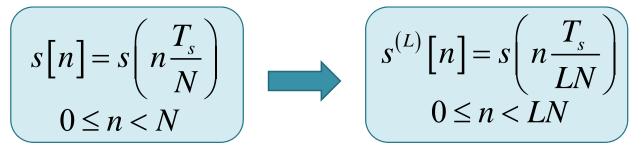


## Oversampling



## Oversampling (2)

- Increase the number of sample points from N to LN on the interval [0, T<sub>s</sub>].
- *L* is called the **over-sampling factor**.



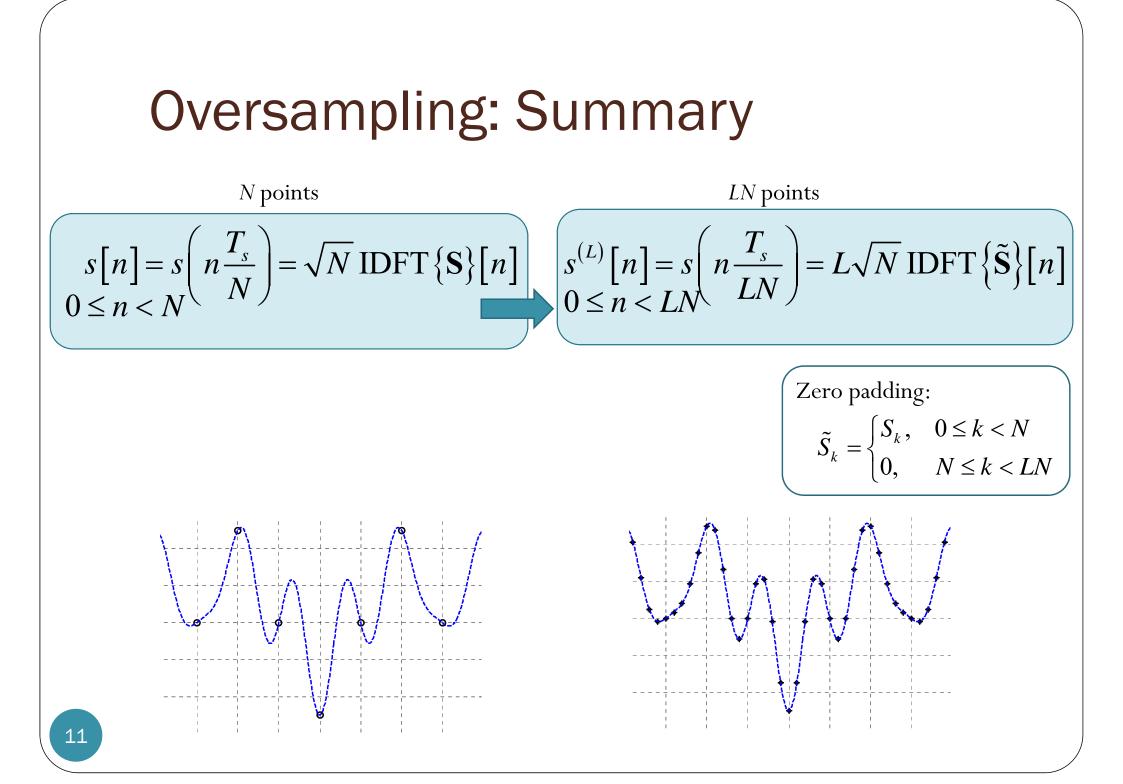
$$s^{(L)}[n] = \frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} S_k \exp\left(j\frac{2\pi k}{\mathcal{I}_{s}'} n\frac{\mathcal{I}_{s}'}{LN}\right) = \frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} S_k \exp\left(j\frac{2\pi kn}{LN}\right)$$

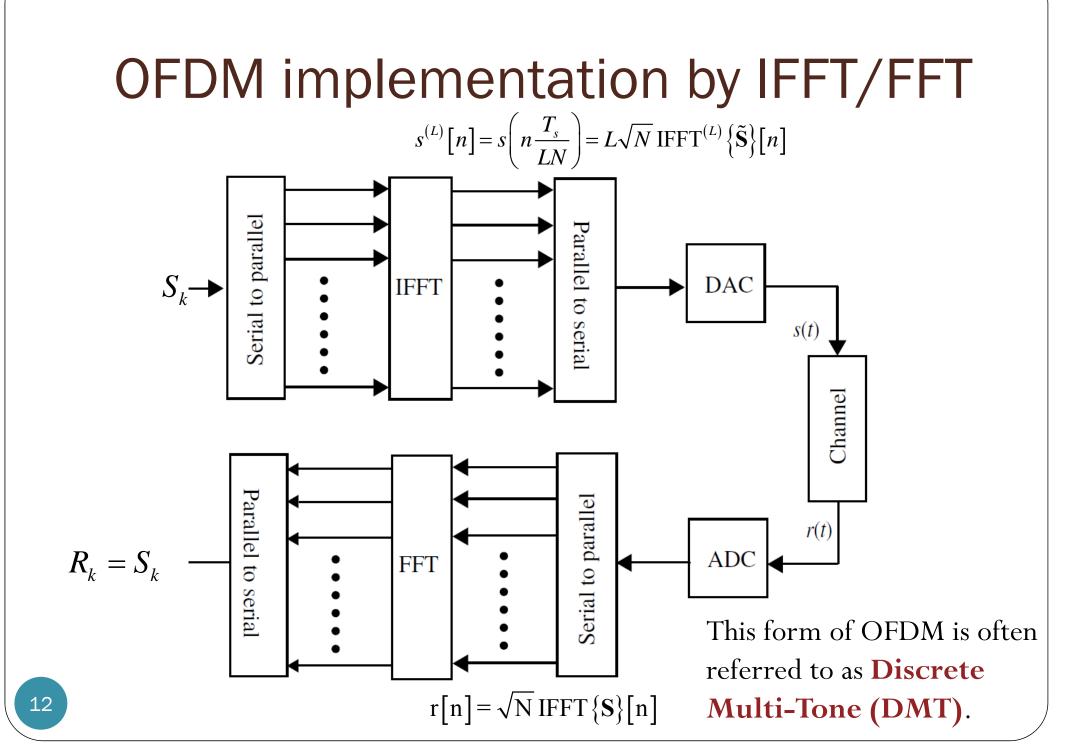
$$= \frac{1}{\sqrt{N}} LN\left(\frac{1}{LN} \sum_{k=0}^{N-1} S_k \exp\left(j\frac{2\pi kn}{LN}\right)\right)$$

$$= L\sqrt{N}\left(\frac{1}{LN} \left(\sum_{k=0}^{N-1} S_k \exp\left(j\frac{2\pi kn}{LN}\right) + \sum_{k=0}^{NL-1} 0 \exp\left(j\frac{2\pi kn}{LN}\right)\right)\right)$$

$$= L\sqrt{N} \left(\frac{1}{LN} \sum_{k=0}^{N-1} \tilde{S}_k \exp\left(j\frac{2\pi kn}{LN}\right)\right) = L\sqrt{N} \operatorname{IDFT}\left\{\tilde{S}\right\}[n]$$

$$Scaling$$





#### **OFDM** with Memoryless Channel

$$h(t) = \beta \delta(t) \qquad [\text{should be } h(t) = \beta \delta(t - \tau)]$$

$$r(t) = h(t) * s(t) + w(t) = \beta s(t) + w(t)$$
Additive white Gaussian noise
$$r[n] = \beta s[n] + w[n]$$

$$FFT \qquad s[n] = \sqrt{N} \text{ IFFT} \{S\}[n]$$

$$R_k = \frac{1}{\sqrt{N}} \text{ FFT} \{r\}[n] = \beta S_k + \frac{1}{\sqrt{N}} W_k$$

Sub-channel are independent.

(No ICI)

#### **Channel with Finite Memory**

Discrete time baseband model:

$$w[n] = \{h^* s\}[n] + w[n] = \sum_{m=0}^{v} h[m]s[n-m] + w[n]$$

[Tse Viswanath, 2005, Sec. 2.2.3]

where 
$$h[n] = 0$$
 for  $n < 0$  and  $n > v$ 

 $w[n] \sim \mathcal{CN}(0, N_0)$ 

We will assume that  $\nu \ll N$ 

Remarks:

Z = X + jY is a complex Gaussian if X and Y are jointly Gaussian.If X, Y is i.i.d.  $\mathcal{N}(0, \sigma^2)$ , then  $Z = X + iY \sim \mathcal{CN}(0, \sigma_Z^2)$  where  $\sigma_Z^2 = 2\sigma^2$  with  $f_Z(z) = f_{X,Y}(\operatorname{Re}\{z\}, \operatorname{Im}\{z\}) = \frac{1}{\pi\sigma_Z^2} e^{\frac{|z|^2}{\sigma_Z^2}}.$ 

#### **OFDM** Architecture

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